

**GREYHOUND US1142 Line**

Kansas City Bus Station

Get The App

The GREYHOUND US1142 bus line (Kansas City Bus Station) has 2 routes. For regular weekdays, their operation hours are:

(1) Kansas City Bus Station: 8:50 PM(2) Dallas Bus Station: 11:45 PM

Use the Moovit App to find the closest GREYHOUND US1142 bus station near you and find out when is the next GREYHOUND US1142 bus arriving.

**Direction: Kansas City Bus Station**

12 stops

[VIEW LINE SCHEDULE](#)

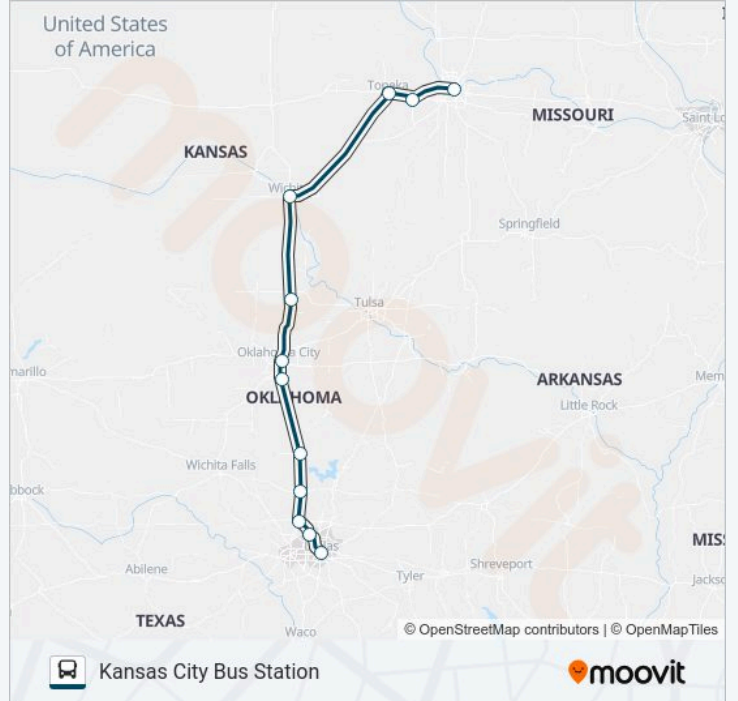
Dallas Bus Station  
Lewisville (Chevron)  
Denton (Exxon)  
Gainesville (Chevron)  
Ardmore (McDonald'S)  
Norman (Sinclair Masters Oil)  
Oklahoma City Bus Station  
Perry (2 Go Express)  
Wichita Bus Stop  
Topeka (Bp To Go)  
Lawrence Bus Stop  
Kansas City Bus Station

**GREYHOUND US1142 bus Time Schedule**

Kansas City Bus Station Route Timetable:

Monday	8:50 PM
Tuesday	8:50 PM
Wednesday	8:50 PM
Thursday	8:50 PM
Friday	8:50 PM
Saturday	8:50 PM
Sunday	8:50 PM

**GREYHOUND US1142 bus Info****Direction:** Kansas City Bus Station**Stops:** 12**Trip Duration:** 779 min**Line Summary:**



**Direction: Dallas Bus Station**

11 stops

[VIEW LINE SCHEDULE](#)

- Kansas City Bus Station
- Lawrence Bus Stop
- Topeka (Bp To Go)
- Wichita Bus Stop
- Oklahoma City Bus Station
- Norman (Sinclair Masters Oil)
- Ardmore (Mcdonald'S)
- Gainesville (Chevron)
- Denton (Exxon)
- Lewisville (Chevron)
- Dallas Bus Station

**GREYHOUND US1142 bus Time Schedule**

Dallas Bus Station Route Timetable:

Monday	11:45 PM
Tuesday	11:45 PM
Wednesday	11:45 PM
Thursday	11:45 PM
Friday	11:45 PM
Saturday	11:45 PM
Sunday	11:45 PM

**GREYHOUND US1142 bus Info**

**Direction:** Dallas Bus Station

**Stops:** 11

**Trip Duration:** 761 min

**Line Summary:**



GREYHOUND US1142 bus time schedules and route maps are available in an offline PDF at [moovitapp.com](https://moovitapp.com). Use the Moovit App to see live bus times, train schedule or subway schedule, and step-by-step directions for all public transit in Lawrence.

© 2024 Moovit - All Rights Reserved